FUZZY IMPULSIVE INTEGRO DIFFERENTIAL EQUATIONS AND RULE BASED SYSTEM WITH MAMDANI’S MODEL

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Abstract

Integral equations are a standout amongst the most helpful scientific instruments in both immaculate and connected Mathematics. They have huge applications in numerous real problems. Many starting and limit esteem problems related with ordinary differential condition (ODE) and partial differential condition (PDE) can be changed into problems of comprehending some surmised essential equations. There exists a broad hypothesis for impartial useful integro differential equations which incorporates subjective conduct of classes of such equations and applications to biological and designing procedures for subtleties. A fuzzy Inference system (FIS) maps fresh contributions to fresh yields. A FIS comprises of four segments: the fuzzifier, inference motor, rule base, and defuzzifier. We can say that Fuzzy logic ideas incorporate fuzzy sets, fuzzy logic administrators, rule-based frameworks, fuzzy maps, and derivation motor and defuzzification strategies. The utilization of fuzzy inference capacities is effectively taken care of even in state space; interestingly, all counts must be numerical and not diagnostic.

Keywords: integro, differential, equation, mamdani’s, model, fuzzy, etc.

1. INTRODUCTION

Integral equations are a standout amongst the most helpful scientific instruments in both immaculate and connected Mathematics. They have huge applications in numerous real problems. Many starting and limit esteem problems related with ordinary differential condition (ODE) and partial differential condition (PDE) can be changed into problems of comprehending some surmised essential equations. For sure, demonstrating such problems utilizing fundamental equations with the correct parameters is simple as well as outlandish in the real problems. For this reason, one way is utilizing some vulnerability measures for dealing with such absence of data. A standout amongst the most and late methodologies is utilizing Zadeh's fuzzy concept. In the recently portrayed (Mamdani) model, the whole information is subjective in light of the fact that we attribute a scope of truth esteems for every factor through the distinctive picked participation capacities.

1.1 Fuzzy Differential Equations

The investigation of fuzzy differential equations (FDE) structures a reasonable setting for mathematical modeling of real world problems in which vulnerabilities or dubiousness invades. Fuzzy
Differential equations are a characteristic method to show dynamical frameworks under vulnerability. The idea of a fuzzy subsidiary was characterized by Chang and Zadeh. It was followed up by Dubois and Prade, who utilized the expansion guideline. The term fuzzy differential equation was presented by Kandel and Byatt. There have been numerous recommendations for the meaning of fuzzy subsidiary to ponder fuzzy differential equations.

The first and the most well-known methodology are utilizing the Hukuhara differentiability for fuzzy-esteem capacities. Under this setting, for the most part the presence and uniqueness of the arrangement of fuzzy differential equations are contemplated. This methodology has a disadvantage: the arrangement winds up fuzzier as time passes by. Consequently, the fuzzy arrangement carries on uniquely in contrast to the fresh arrangement. The idea of fuzzy subsidiary as an augmentation of the Hukuhara subordinate and fuzzy indispensable, which was equivalent to what Dubois and Prade proposed.

2. EXISTENCE AND UNIQUENESS RESULTS FOR FUZZY IMPULSIVE INTEGRO DIFFERENTIAL EQUATIONS

There exists a broad hypothesis for impartial useful integro differential equations which incorporates subjective conduct of classes of such equations and applications to biological and designing procedures for subtleties, however, the solid model is the radio cardiogram, where the two compartments relate to one side and right ventricles of the pneumatic and systematic flow. Funnels turning out from and returning into a similar compartment may speak to shunts, and the equation speaking to this model is nonlinear impartial volterra integro differential equations in. Hence, there has been an expanding enthusiasm for examining equations that can be portrayed in the structure

\[
\frac{dx(t)}{dt} = a(t)x(t) + \int_{0}^{t} k(t, s, x(s))ds + f(t, x(t)), \quad t \in J,
\]

\[
\Delta x_{k} = l_{k}(x(t_{k})), \quad k = 1, 2, 3, ..., m,
\]

\[
x(0) = x_{0},
\]

Where \(x\) represents the history of \(x\) at \(t\) and \(a:J \rightarrow E_{N}\) is a fuzzy co-efficient. \(E_{N}\) is the set of all upper semi-continuous, convex, normal fuzzy numbers with bounded \(\alpha\)-level intervals.

3. FUZZY LOGIC BASED INFERENCE SYSTEM

A fuzzy Inference system (FIS) maps fresh contributions to fresh yields. A FIS comprises of four segments: the fuzzifier, inference motor, rule base, and defuzzifier. The fuzzifier maps information numbers into relating fuzzy enrollment esteems. The inference motor characterizes mapping from information fuzzy sets to yield fuzzy sets. It decides how much the precursor (ancestor) part is fulfilled for each standard. In the event that the predecessor part of the standard has more than one proviso, fuzzy administrators are applied to get a number that speaks to the consequence of the forerunner part for that standard. Yields of all guidelines are then collected. The defuzzifier maps the yield fuzzy sets into a fresh number. The for the most part utilized defuzzification strategy is the centroid technique.
In designing a FIS we need fuzzy rules. Regularly, these rules are gotten from master's learning. Be that as it may, it is likewise conceivable to create fuzzy rules from test information focuses. Wang and Mendel (1991) have proposed a systematic strategy for extricating fuzzy rules from test information focuses.

The semantic rules are utilized to characterize the connection between the info and the yield, yet how precisely are the yield fuzzy qualities decided? There are a few different ways to decide the appropriate response dependent on the sources of info, predominantly the Mamdani, Larsen, Takagi-Sugeno-Kang, and Tsukamoto inference and conglomeration strategies. Right off the bat, we should depict the essential general set of rules, they will be a set of rules that have one contribution to a fuzzy set and one yield in a fuzzy set.

If $x$ is $A_i$ then $y$ is $B_i$, $i = 1, 2, ..., n$

Let us look at a system that has two input membership functions ($A_1, A_2$) and two output membership functions ($B_1, B_2$). These membership functions, shown below (Fig.1 a & b), define the fuzzy sets $A$ and $B$ in the above general inference rule.

A1 and A2 are shown on the left, with A1 in blue and A2 in green. On the right B1 is blue and B2 is green. We will be using the Mamdani inference model to combine the sets and rules. If the input value has membership in a function, than any rule using that membership function is said to 'fire' and produce a result. These results are then aggregated using the Mamdani model (or a different model).

4. FUZZY RULE BASED SYSTEM
MAMDANI'S MODEL

Fuzzy linguistic descriptions are formed representations of systems made through fuzzy IF-THEN rules.

In the simple one input and one output example given in fig.2, the rules were simply that if input is low output is low and if input is high output is high.

If (a set of conditions) as satisfied THEN (a set of consequents) can be inferred.

If - then rules are coded in the form. In a multi input system, the input vector has values for $x_1, x_2, ..., x_n$. The membership functions are designated as $A_1, A_2$ etc. Then,

If \( \left( x_1 \text{ is } \hat{A}_1, \; x_2 \text{ is } \hat{A}_2, \ldots, x_n \text{ is } \hat{A}_n \right) \) Then \( \left( y_1 \text{ is } \hat{B}_1, \; y_2 \text{ is } \hat{B}_2, \ldots, y_n \text{ is } \hat{B}_n \right) \).

there must be severe flood warning.

Here, heavy, strong and severe and fuzzy sets qualifying the variables rain, wind and flood warming respectively. Using If-Then type fuzzy rules converts the fuzzy input to the fuzzy output (figure 2).
5. TAKAGI-SUGENO MODIFICATION TO MAMDANI’S MODEL

In 1985 and later in 1988, Takagi, Sugeno and Kang delivered an altered fuzzy inference system for the Mamdani’s model. In the recently portrayed (Mamdani) model, the whole information is subjective in light of the fact that we attribute a scope of truth esteem for every factor through the distinctive picked participation capacities. Likewise, for the yield required, we attribute a set of enrollment works over the range estimation of the yield variable. Hence, given a subjective set of information, for example, given in the table underneath, one can totally recommend a Fuzzy model of the system.
Table 1 A Fuzzy Inference System of Mamdani– Baby Nutrition Example

<table>
<thead>
<tr>
<th>Height of a Baby (within one year)</th>
<th>Weight of Baby</th>
<th>Prescribed nutrition value per meal</th>
</tr>
</thead>
<tbody>
<tr>
<td>Low (0 – 30 cm)</td>
<td>Light (1-2 kg)</td>
<td>High (150-250 mg)</td>
</tr>
<tr>
<td>Normal (20-70 cm)</td>
<td>„</td>
<td>Normal (75-125 mg)</td>
</tr>
<tr>
<td>Tall (60-100 cm)</td>
<td>„</td>
<td>Low (50-100 mg)</td>
</tr>
<tr>
<td>Low</td>
<td>Normal (1.5 -2.5 kg)</td>
<td>Low</td>
</tr>
<tr>
<td>Normal</td>
<td>„</td>
<td>Normal</td>
</tr>
<tr>
<td>Tall</td>
<td>„</td>
<td>High</td>
</tr>
<tr>
<td>Low</td>
<td>Weighty (2.0-4 kg)</td>
<td>Normal</td>
</tr>
<tr>
<td>Normal</td>
<td>„</td>
<td>High</td>
</tr>
<tr>
<td>Tall</td>
<td>„</td>
<td>High</td>
</tr>
</tbody>
</table>

Fuzzy logic has the capacity to mirror the human personality to successfully reason out from realities of perception, regardless of whether such actualities are estimated rather than precise. In spite of the fact that there are significant territories of cover between neural systems, Fuzzy logic, and probabilistic thinking, when all is said in done they are complimentary as opposed to focused. There are numerous approaches to combine neural systems and Fuzzy logic methods.

6. CONCLUSION

We can say that Fuzzy logic ideas incorporate fuzzy sets, fuzzy logic administrators, rule-based frameworks, fuzzy maps, and derivation motor and defuzzification strategies. The utilization of fuzzy inference capacities is effectively taken care of even in state space; interestingly, all counts must be numerical and not diagnostic. Fuzzy logic is currently genuinely settled in different fields and state space control is a typical method for ideal procedure control. In the recently portrayed (Mamdani) model, the whole information is subjective in light of the fact that we attribute a scope of truth esteems for every factor through the distinctive picked participation capacities. The vast majority of the pages here have recently presented these extremely same techniques.

REFERENCES


