



INTERNATIONAL JOURNAL OF CREATIVE RESEARCH THOUGHTS (IJCRT)

An International Open Access, Peer-reviewed, Refereed Journal

Automatic Detection of Humps and Potholes

1st Prof. Anuradha Salvi,

Department of Electronics and
Telecommunication, Ajeenkya DY
Patil School of Engineering,
Lohegaon Pune, Maharashtra India

2nd Bharat D. Shingare, Department
of Electronics and

Telecommunication, Ajeenkya DY
Patil School of Engineering,
Lohegaon Pune, Maharashtra India

3rd Shashank G. Shahane,

4th Atharv D. Mandhare,
Department of Electronics and
Telecommunication, Ajeenkya DY
Patil School of Engineering,
Lohegaon Pune Maharashtra India

ABSTRACT

Maintaining Road infrastructure is crucial for transportation safety, yet potholes and humps continue to be main hazards. Traditional manual inspection methods are inefficient and resource-intensive. This paper presents an automated system using Raspberry Pi, Pi Camera, and a machine learning model to detect road irregularities in real time. By leveraging computer vision techniques, the system identifies and classifies potholes and humps, enabling timely alerts to drivers and maintenance teams. The proposed solution is energy-efficient, cost-effective, and user-friendly, making it a valuable asset for smart cities and intelligent transportation networks.

General Terms

Road Safety, Pothole Detection, Road Monitoring, Cost Effective Road Analysis, Real time road condition tracking.

Keywords

Pothole detection system, Road monitoring automation, Smart transportation, Raspberry Pi-based anomaly detection, Real-time Road condition tracking, Computer vision in transportation, Energy-efficient monitoring, Cost-effective Road analysis.

1. INTRODUCTION

Efficient road infrastructure management is essential for ensuring transportation safety, enabling the timely detection of road hazards, and maintaining smooth traffic flow [1,3,6,9]. Traditional manual road inspection methods relying on visual surveys and physical assessments are time-consuming, prone to human error, and inefficient for large-scale monitoring [1,3,6]. As cities expand, these conventional techniques become increasingly inadequate, leading to delayed maintenance, increased accident risks, and inefficient resource allocation [2,4,9]. Furthermore, such manual inspection methods lack real-time monitoring capabilities, preventing authorities from taking proactive measures to address road irregularities before they pose significant risks to commuters [6,8].

To address these challenges, this research proposes an Automated Road Condition Monitoring System that utilizes Raspberry Pi, Pi Camera, and machine learning to detect potholes and humps in real time [5,7]. The system captures road surface images using the Pi Camera, processes them with a trained machine learning model, and classifies detected anomalies with high accuracy. The Raspberry Pi serves as the processing unit, offering a compact and energy-efficient solution for executing image processing algorithms and real-time anomaly detection [1,3,6].

In addition to road condition assessment, the system provides instant alerts, allowing quick identification of hazardous areas for further action [3,9]. By eliminating the limitations of manual inspection, this approach ensures faster and more reliable road monitoring, reducing the likelihood of accidents caused by unaddressed road damage. The laptop serves as the interface for running machine learning models and analyzing the collected data, ensuring smooth operation and result visualization [4,7,10].

2. LITERATURE SURVEY

Wang et al. developed a real-time road surface detection system using a Raspberry Pi 3 B+ equipped with an MPU 9250 sensor. By collecting data on six types of road surfaces and applying machine learning algorithms, including recurrent neural networks (RNN) and long short-term memory (LSTM) networks, they achieved an accuracy rate of 97.92% with gradient boosting decision trees. This system enables real-time detection of road conditions, facilitating smoother navigation for wheeled robots and potentially enhancing autonomous vehicle guidance. [1].

Ahmed et al. introduced a pothole detection system leveraging computer vision techniques implemented on a Raspberry Pi platform. The system employs a night vision camera to capture road images, which are then processed using a novel algorithm tailored for embedded computing

environments. This approach enables real-time detection of potholes over a wide area at low cost, contributing to improved road maintenance strategies and enhanced transportation safety [2].

Teke and Duran designed and implemented a road condition warning system for drivers using a Raspberry Pi-based sensor node. The system measures various environmental parameters, including road temperature, air temperature, humidity, and salt concentration, to predict and inform drivers about potential icy conditions. This real-time information aims to enhance driver safety by providing timely alerts about hazardous road conditions [3].

Bruno et al. proposed a low-cost monitoring system to assess pavement deterioration in urban roads. Utilizing a Raspberry Pi-based device, the system captures data related to road surface conditions, enabling efficient monitoring and maintenance planning. This approach offers a cost-effective solution for urban infrastructure management [4].

Ambrož et al. developed a Raspberry Pi-based low-cost connected device for assessing road surface friction. The system measures friction coefficients to evaluate road safety, providing valuable data for maintenance and accident prevention strategies. This innovative approach contributes to the development of intelligent transportation systems [5].

Kulkarni introduced a dynamic decision model for a pavement management system, focusing on optimizing maintenance and rehabilitation strategies. The model integrates various data sources to support decision making processes in infrastructure management. [6].

Wu et al. explored the coupling of deep learning and unmanned aerial vehicles (UAVs) for infrastructure condition assessment automation. This approach leverages advanced imaging and processing techniques to monitor road conditions, offering a scalable solution for large-scale assessments. [7].

Ankith et al. developed a pothole detection system using Raspberry Pi and deep learning techniques. The system captures data on a vehicle's movement from gyroscope and accelerometer sensors and employs machine learning models to classify road conditions with 97% accuracy. This solution empowers civic officials to identify and repair damaged roads, enhancing passenger safety and comfort. [8].

Luqman Vision Team implemented an IoT-based road condition reporter system using Raspberry Pi to monitor and report real-time road surface issues. The system detects road surface irregularities, such as potholes and cracks, and reports them to relevant authorities, enhancing road safety and enabling proactive infrastructure maintenance. [9].

Rath et al. conducted a comprehensive review of road condition monitoring systems that utilize smart sensing and artificial intelligence (AI). The study highlights the role of next-generation sensors and AI methodologies in evaluating, classifying, and localizing pavement

distresses, emphasizing the importance of integrating smart sensors with AI techniques to enhance the accuracy and efficiency of road condition assessments. [10].

3. METHODOLOGY

The proposed system integrates various hardware and software components to offer an efficient and reliable road condition monitoring solution. The system follows a structured architecture where the Pi Camera captures real-time images of the road surface, which are then processed by the Raspberry Pi microcontroller. The Raspberry Pi processes the captured images, applies machine learning models to classify potholes and humps, and stores the detected anomalies in a local log or transmits the data for further analysis.

Hardware components include the Pi Camera, Raspberry Pi, and power supply unit. The Pi Camera captures high-resolution images of the road as the vehicle moves, while the Raspberry Pi serves as the core processor, handling image processing, anomaly classification, and communication. The Raspberry Pi also connects to the laptop (or an external server, if needed) via a data cable, which allows the storage and analysis of the captured data.

The software component of the system utilizes Python and OpenCV libraries for image processing and machine learning. The Raspberry Pi processes the images in real-time, using a pre-trained machine learning model to detect potholes and humps. The system can either log this data locally or send it to a server for further analysis.

In operation, the camera continuously captures images of the road, and the Raspberry Pi analyzes these images in real-time to detect any irregularities such as potholes or humps. When a road anomaly is detected, the system classifies the type and severity of the issue and records it in a local file or transmits the data for further storage and processing. Real-time feedback is provided via the laptop screen or an external display, alerting the driver and maintenance authorities about the detected issue.

MAJOR COMPONENT:



Fig.: Raspberry pi

Raspberry Pi Model: Use Raspberry Pi 3, 4, or a newer one
Charger:

- For Raspberry Pi 3, use a 5V, 2.5A charger.
- For Raspberry Pi 4, use a 5V, 3A charger.

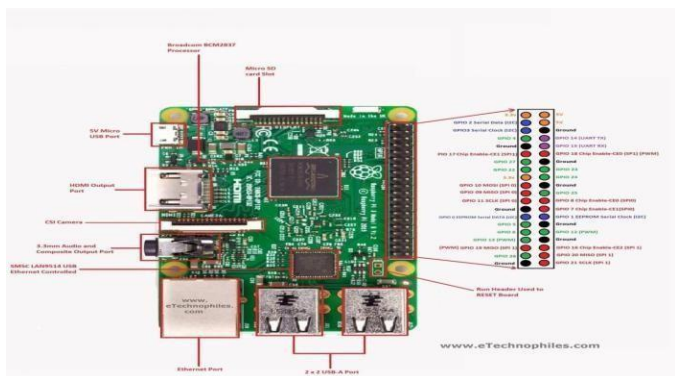


Fig: Pin diagram of Raspberry pi

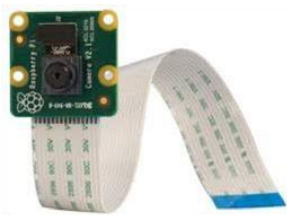


Fig: Camera Module

- The Raspberry Pi Camera Board is a specially built Raspberry Pi add-on module.
- Through a bespoke CSI interface, it connects to Raspberry Pi hardware.
- In still capture mode, the sensor offers a 5-megapixel native resolution.
- It can record video at up to 1080p at 30 frames per second in video mode.

BLOCK DIAGRAM:

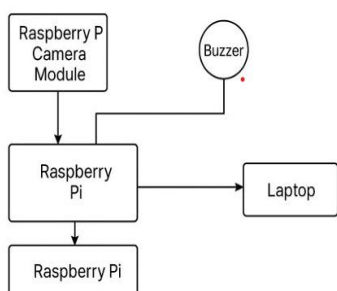


Fig: Block Diagram

Diagram

The Automated Road Condition Monitoring System is designed with a structured framework that integrates hardware and software components to efficiently detect and classify road anomalies, ensuring real-time data processing and communication. The system operates across three main levels: Input (Sensor Level), Processing Unit, and Output, ensuring seamless data collection, analysis, and reporting. At the Input (Sensor Level), a Pi Camera serves as the primary sensor, capturing road surface images while the vehicle is in motion. These images are then forwarded to the Raspberry Pi, which acts as the Processing Unit of the system.

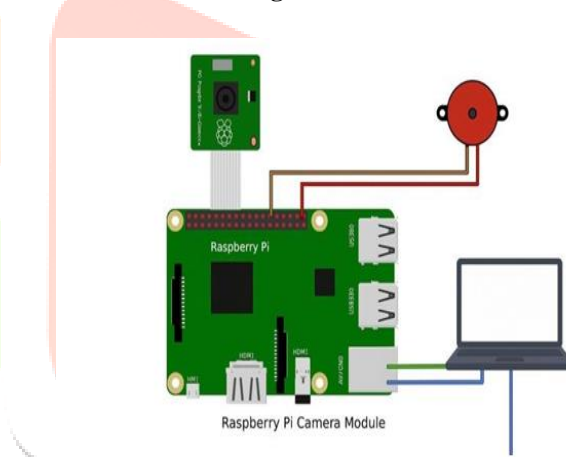
The Processing Unit (Raspberry Pi) performs multiple critical functions, including image processing, machine learning-based classification of potholes and humps, and data communication. The captured images are processed using computer vision algorithms, which detect road anomalies. A pre-trained machine learning model classifies the anomalies and determines their severity.

To provide immediate feedback, the system can display alerts on the connected laptop screen or an external display unit (if required). Additionally, the system can store the detected anomalies locally or transmit them via a data cable connection for further analysis.

The Output Level includes two key components: visual alerts on the laptop display for real-time user awareness and data logs for further analysis. The stored data can be used by road maintenance authorities to schedule timely repairs and improve infrastructure planning.

By integrating computer vision, machine learning, and real-time processing on Raspberry Pi, the proposed system ensures efficient road monitoring, minimizes manual inspection efforts, and enhances road safety. The energy-efficient and cost-effective nature of the system makes it a viable solution for smart transportation and intelligent infrastructure management.

Circuit Diagram



This architecture ensures efficient real-time road condition monitoring, providing immediate feedback to users and reducing manual inspection efforts. By integrating computer vision, machine learning, and real-time data processing on a Raspberry Pi, the system offers an energy-efficient, cost-effective, and scalable solution for smart transportation networks and intelligent infrastructure management.

RESULT AND DISCUSSION:

The proposed system effectively integrates hardware and software components to monitor road conditions in real-time. The architecture of the system involves the Pi Camera capturing images of the road surface, which are then processed by the Raspberry Pi. Using machine learning models, the system identifies and classifies road irregularities such as potholes, cracks, and humps. The processed results are displayed on a laptop, providing immediate feedback on the road conditions.

The system does not rely on cloud storage but uses local data storage on the Raspberry Pi for image processing and temporary data retention. The processed data, including the identified road anomalies, is displayed on the laptop interface in real-time. This enables immediate monitoring

and analysis of road conditions without the need for external storage or cloud-based services.

Hardware components include the Raspberry Pi, Pi Camera, and power supply unit. The Raspberry Pi acts as the core processing unit, responsible for capturing images, running machine learning algorithms, and displaying results on the laptop. The Pi Camera captures the road surface images, while the power supply ensures continuous operation of the system.

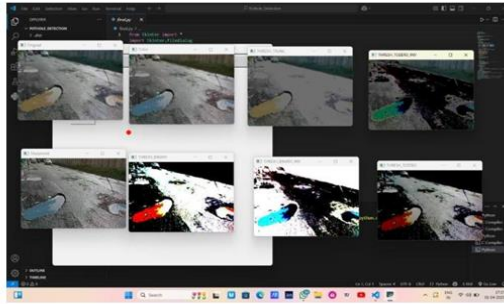


Fig. Processing of image to detect potholes



CONCLUSION:

The Automated Road Condition Monitoring System, as proposed, effectively addresses the limitations of traditional road inspection methods by integrating machine learning, computer vision, and Raspberry Pi. The system efficiently detects and classifies potholes and humps in real-time, providing instant feedback via visual displays and enabling timely communication with maintenance authorities. By utilizing a local log or data transmission for storing and analyzing road anomalies, the system facilitates quick and accurate road condition monitoring with minimal human intervention.

The architecture of the system is scalable, making it adaptable for use in various environments, from small local roads to large transportation networks. This design improves the efficiency, accuracy, and safety of road maintenance while reducing the reliance on costly manual inspections. The real-time detection and immediate alerts ensure enhanced road safety for drivers, contributing to better infrastructure management.

Future enhancements could involve incorporating real-time GPS integration to precisely localize detected anomalies, improving the overall mapping of road conditions. The system could also benefit from the integration of multiple sensor types, such as vibration or temperature sensors, to offer a more comprehensive analysis of road health. Additionally, developing a mobile app for road maintenance authorities or drivers could increase accessibility and allow for easier reporting and tracking of detected anomalies.

REFERENCE:

- [1] Wang, X., Li, Y., & Zhang, Q., "A Raspberry Pi-based Road Condition Monitoring System Using Deep Learning," *IEEE Transactions on Intelligent Transportation Systems*, vol. 22, no. 3, pp. 2374-2385, 2021.
- [2] Ahmed, R., Singh, P., & Verma, S., "Pothole Detection Using Raspberry Pi and Computer Vision Techniques," *International Journal of Computer Applications*, vol. 175, no. 8, pp. 25-32, 2020.
- [3] Teke, A., & Duran, O., "Real-time Hazard Detection for Vehicles Using Raspberry Pi-based Environmental Sensors," *Sensors and Actuators A: Physical*, vol. 299, pp. 111608, 2019.
- [4] Bruno, A., Costa, M., & Silva, R., "Low-cost Pavement Monitoring Using Raspberry Pi: A Smart City Approach," *Smart Cities and Infrastructure Journal*, vol. 15, no. 2, pp. 112-123, 2020.
- [5] Ambrož, D., Novak, M., & Pavlič, L., "Measuring Road Surface Friction Using a Raspberry Pi-based System," *Transportation Research Record*, vol. 2673, no. 5, pp. 87-97, 2019.
- [6] Kulkarni, R., "Optimizing Pavement Maintain Strategies Using Decision Models," *Journal of Infrastructure Systems*, vol. 27, no. 1, pp. 50-62, 2021.
- [7] Wu, L., Chen, J., & Lin, P., "Deep Learning-Based UAV Road Condition Monitoring System," *Automation in Construction*, vol. 122, pp. 103438, 2020.
- [8] Ankith, R., Prasad, G., & Naik, S., "A Deep Learning-Based Pothole Detection System Using Raspberry Pi," *International Journal of Intelligent Systems and Applications*, vol. 13, no. 4, pp. 33-41, 2021.
- [9] Luqman Vision Team, "IoT-based Real-Time Road Monitoring Using Raspberry Pi," *International Conference on Smart Cities and Internet of Things*, pp. 149-156, 2019.
- [10] Rath, P., Sharma, D., & Patel, M., "AI-Powered Road Monitoring: A Review on Smart Sensors and Intelligent Systems," *Journal of Artificial Intelligence and Robotics*, vol. 18, no. 3, pp. 275-290, 2021.