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Pesticide Spraying Robot Robot

[1]Swathi K, [2]Dakshayani S, [3]Likitha SR, [4] Rakshitha Y R, [5] Shivaleela
[1]Assistant Professor, [2]Student, [3]Student, [4] Student, [5] Student
[1]Deptof Electrical and Electronics Engineering
GSSSIETW, Mysuru, India

Abstract: A Pesticide Spraying Robot (PSR) using the Arduino IDE integrates advanced agricultural technologies to optimize pesticide use, enhancing both efficiency and sustainability. The system employs a variety of sensors, including temperature, humidity, soil moisture, and light sensors, all connected to an Arduino microcontroller. This setup allows for real-time monitoring of environmental conditions and pest activity. By processing the collected data, the Arduino can trigger precise pesticide application based on predefined conditions, ensuring that chemicals are used only when necessary and in optimal amounts. The Arduino IDE facilitates the creation of custom programstoanalyzesensordataandautomatepesticidedelivery. Actuators such as solenoid valves and GPS-enabled robotic sprayers can be controlled to apply pesticides accurately, minimizing waste and reducing the impact on non-target organisms. Communication modules like Wi-Fi or Bluetooth enable remote monitoring and control, providing farmers with the flexibility to manage pest control operations from any location. This integration of real-time data analytics and automation leads to significant cost savings, improved crop yields, and reduced environmental harm. Accessible and affordable, the Arduinoplatformmakes PSRfeasible for small- scalefarmersandthoseindevelopingregions.Theuser-friendly nature of the Arduino IDE, combined with extensive online resourcesandcommunitysupport,facilitatestheimplementation andcustomizationofthesystem.Byoptimizingpesticideuse,the PSR not only enhances economic viability for farmers but also supports environmental sustainability by reducing chemical runoff, protecting soil health, and preserving biodiversity. This innovative approach represents a significant advancement in sustainable agricultural practices, leveraging technology to address the challenges of modern pest management.

Index Terms - Pesticide sprayer, remote controlled, agricultural use, Arduino IDE

I. INTRODUCTION

A Pesticides Spraying Robot (PSR) using the Arduino IDE represents an innovative fusion of agriculture and technology, offering an affordable and scalable solution for optimizing pesticide use. Leveraging the Arduino platform, the system integrates sensors and actuators to monitor real-time environmental conditions,crophealth, andpest activity. The Arduino microcontroller processes data from temperature, humidity, soil moisture, and light sensors to enable precise pesticide application, reducing chemical use and environmental impact. Custom programs developed on the Arduino IDE analyze sensor data to automate pesticide application based on specific conditions. Solenoid valves connectedtosprayerscanbecontrolledbytheArduino to deliver pesticides only when optimal environmental thresholds are met. This targeted application reduces costs, enhances efficacy, and minimizes harm to non-target organisms. CommunicationmoduleslikeWi-FiorBluetoothallow forremotemonitoringandcontrol,givingfarmersreal- time insights and decision-making capabilities from anywhere. The affordability and user-friendliness of the Arduino platform makeit accessible to small-scale farmersandthoseindevelopingregions.Theextensive library support and active community facilitate the integration of advanced functionalities, such as machine learning algorithms for improved pest prediction

accuracy.By optimizing pesticide use and promoting sustainable farming practices, an Arduino-based PSR contribute to environmental conservation, protecting water bodies from contamination and preserving soil health and biodiversity. This technology-driven approach to pest management exemplifies the future of sustainable agriculture.

II.RELATEDWORK

[1] The paper titled “development of smart pestide Spraying Robot" by Pvr Chaitanya, Dileep Kotte, A. Srinath, and K. B. Kalyan, published in the International Journal of Recent Technology and Engineering (IJRTE) in January 2020, discusses the design and implementation of an intelligent robotic system for pesticide spraying in agricultural fields. This smart robot is equipped with advanced sensors and control systems to optimize the spraying process, ensuring precise application of pesticides, reducing waste, and minimizing human exposure to harmful chemicals. The authors highlight the technological innovations involved, such as automation and IoT integration, which enhance the efficiency and effectiveness of pest control practices in farming. The research emphasizes the potential benefits of such robotic systems in terms of improved crop yields, reduced environmental impact, and overall agricultural productivity.

[2] The paper titled "Development of Smart Pesticide Spraying Robot" by Pvr Chaitanya, Dileep Kotte, A. Srinath, and K. B. Kalyan, published in the International Journal of Recent Technology and Engineering (IJRTE) in January 2020, discusses the design and implementation of an intelligent robotic system for pesticide spraying in agricultural fields. This smart robot is equipped with advanced sensors and control systems to optimize the spraying process, ensuring precise application of pesticides, reducing waste, and minimizing human exposure to harmful chemicals. The authors highlight the technological innovations involved, such as automation and IoT integration, which enhance the efficiency and effectiveness of pest control practices in farming. The research emphasizes the potential benefits of such robotic systems in terms of improved crop yields, reduced environmental impact, and overall agricultural productivity

[3] The paper titled "Agricultural Robot — A Pesticide Spraying Device," published in the International Journal of Future Generation Communication and networking in 2020, details the creation and implementation of a robotic system designed to enhance the precision and efficiency of pesticide application in agriculture. This robotic device is equipped with ultrasonic sensors and a versatile autonomously through agricultural fields and applies pesticides accurately to target areas. The research emphasizes the system's ability to reduce the amount of pesticides used, thereby lowering environmental impact and protecting beneficial insects. By integrating IoT and real-time data processing, the robot can adapt to various field conditions and make informed decisions, promoting sustainable agricultural practices and improving crop yields

[4] The paper titled "Development of Smart Water Spraying System" by P. Rajesh Kanna and R. Vikram, published in the International Journal of Recent Technology and Engineering (IJRTE), focuses on the design and implementation of an intelligent system for automated water spraying in agricultural settings. The research addresses the need for efficient water management and aims to enhance irrigation practices using advanced technologies. By integrating sensors and automation, the system can monitor soil moisture levels and automatically activate the spraying mechanism as needed, thereby optimizing water usage and ensuring consistent crop hydration. This approach not only conserves water but also reduces manual labor and enhances crop yield reducing wastage and environmental contamination. The system is equipped with GPS technology for accurate location tracking and mapping, allowing for precise navigation across agricultural fields.

III. OBJECTIVES

1. Reduce direct exposure to harmful pesticides by utilizing remote control technology, thereby protecting farmers' health.

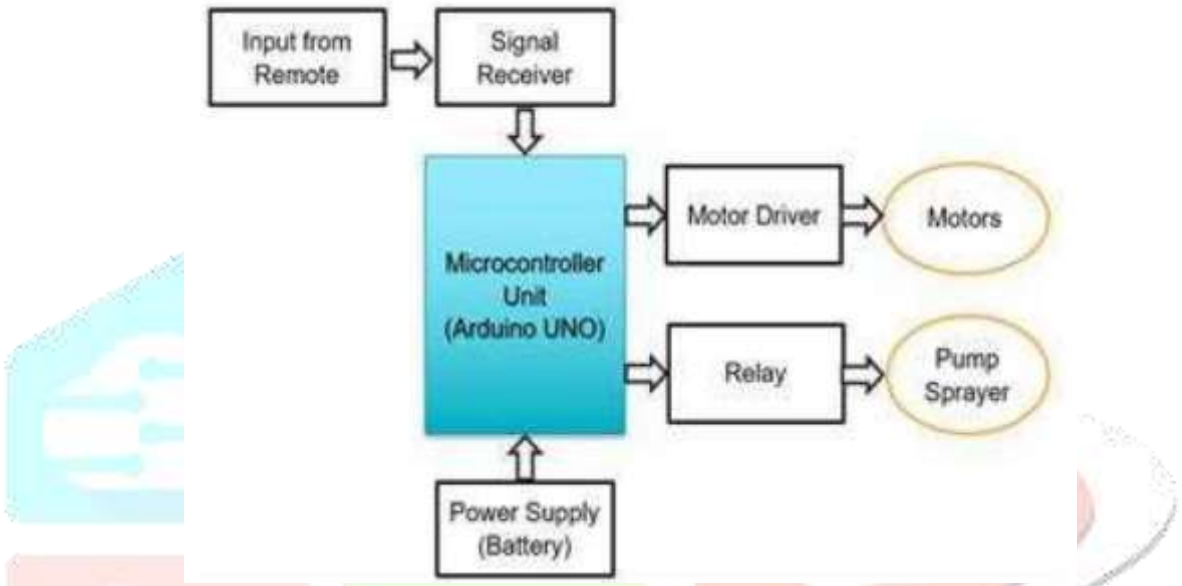
2. Achieve more accurate and consistent pesticide application through automated spraying mechanisms, ensuring uniform distribution across large fields.

3. Create an intuitive and accessible remote control interface that simplifies operation for farmers, making advanced technology usable for all

IV. METHODOLOGY

The Method that using is an Autonomous bot. This serves as helping hand to the farmers by replacing the manual farming technique with the modern farming technique. In our proposed method, the bot will control by using 2.4GHz Radio Frequency Wireless Controller. It reduces the workload of the farmers by sprinkling pesticides by its own. Automation as a part of solution. The main concept of this bot is to make an autonomous robot with the help of an Arduino controller to reduce the health issues of the farmers. In our proposed system it consists of three parts, they are:-

1. Input unit.
2. Spray and Control Processing unit.
3. Output unit.



The purpose of the input unit is to give the power supply for all over the circuit and it will act as a storage device too for saving the pesticide liquid. Spray and Control Processing: The main component of the circuit is Arduino Uno controller and it is also known as Heart of the robot. A driver circuit is connected to Arduino, which is used for the movement of the robot. A pesticide pump is also used for transferring of liquid pesticide to the sprayer head from the storage tank. The output unit consists of direction control unit which is used for controlling the directions via wirelessly. As per our directions, the spraying unit will spray the fertilizers to the plants. In this system consists of Arduino Uno board, power supply, driver module, prototype car module and RF and receiver module. It is a driver motor 16 pin IC it is used for driving the robot on specific directions as per our instructions. The aim of the project is to design a pesticide spraying bot. environmental concerns associated with conventional pesticide application methods. Central to the use of Al algorithms that analyze real-time data to determine the precise amount of pesticide required. This data-driven approach ensures targeted application, reducing wastage and environmental contamination. The system is equipped with GPS technology for accurate location tracking and mapping, allowing for precise navigation across agricultural fields. It also incorporates various sensors to monitor environmental conditions and plant health, further refining the spraying process. The design emphasizes energy efficiency, utilizing low-power components and, where feasible, renewable energy sources like solar panels. Field trials demonstrated the system's capability to significantly cut down on pesticide use while maintaining or improving pesticide control effectiveness. Additionally, the cost-effectiveness of the system is highlighted, as it reduces the amount of pesticide needed and optimizes labor costs. The paper concludes that the smart spraying system presents a viable, eco-friendly, and economically beneficial alternative to traditional pest management practices with a view of spraying pesticides all over the crop. The power supplies with +12v&-12. A sprayer is used for spraying the pesticides, where sprayers are commonly used for projection of water, weed killers, pest maintenance chemicals etc. Here L293D module is used. It is a driver motor 16 pin IC it is used for driving the robot on specific directions as per our instructions. The aim of the project is to design a pesticide spraying bot with a view of spraying pesticides all over the crop

Figure4.1 Block Diagram

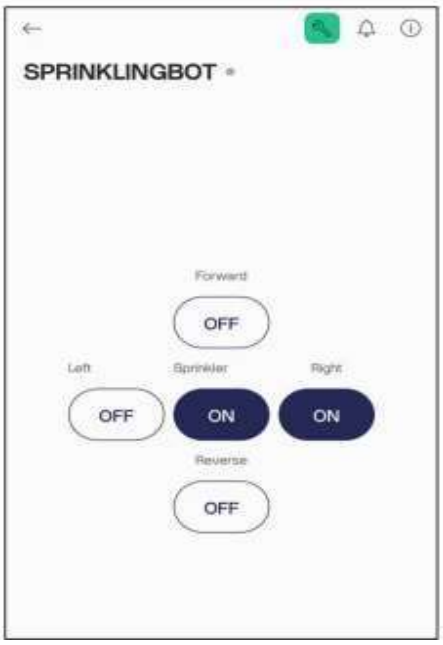


Figure4.2RemoteControlsofthemodel

Figure4.3 Flowchart

V. HARDWARE DESCRIPTION

TheconstructionofPesticidesprayingmachine consistsofaframewhichisusedfor mounting he components such as D.C encoder motor, Battery. The base is used to carry the whole machine. The movement of the robot is controlled by the commands given to the Arduino wirelessly from a safe distance via a radio frequency controller Now it is only left with the spraying mechanism and the storage device for pesticide with the spraying mechanismthatusesDCmotorforsprayingthe pesticides,itconsistsofanarmandamultipoint sprayrodisplacedon.Wecanrotateandadjust the nozzle cap by which we can control the fineness of spraying of pesticide. The motor pump that is used in the robot is submersible. That means one part of pump is used to insert thepipeandotherpartiskeptoutside.A12vDC supplyisusedforthesupplyanditisconnected tothebattery.Thecompletemechanism works onbattery.Thistotalarrangementisusefulagriculturefield bot.

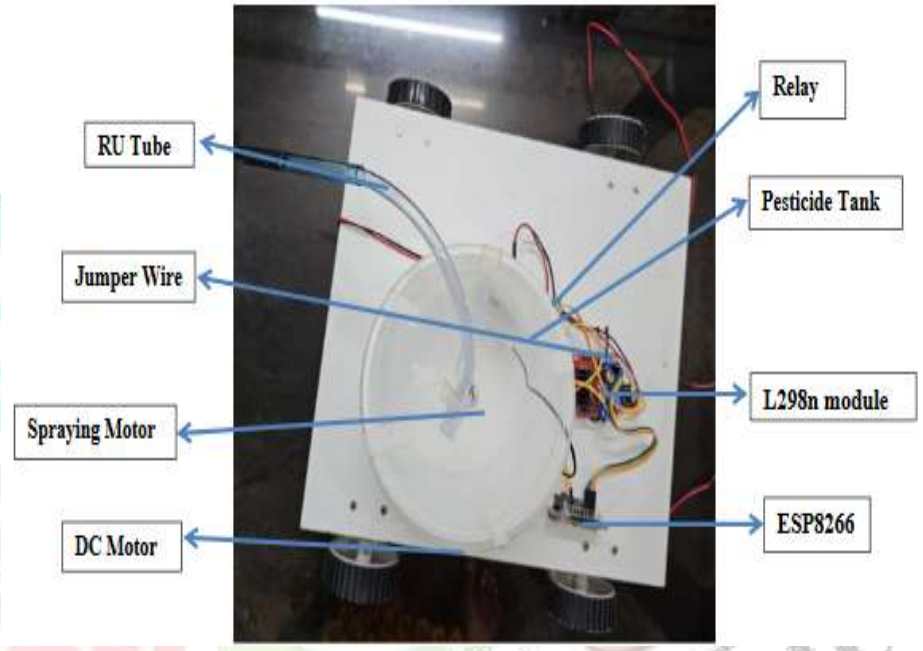


Figure5.3Working Mode

VI. RESULTS, CONCLUSION AND FUTURE SCOPE

6.1 Results

- An efficient system was produced to spray pesticides without human intervention.
- A remote system that can be operated by the farmers without actually touching the pesticides was designed.
- The use of pesticides and time for pesticide spraying can be managed efficiently.

6.2 Conclusion

"This project demonstrates significant advancements in pesticide application through remote control technology. Achieving precise application with reduced labor and time requirements, it promises improved crop health and environmental sustainability. Future directions involve refining system capabilities and conducting extensive field trials for broader agricultural integration."

6.3 Future Scope

- Enhanced Technology Integration: Explore integrating AI or machine learning algorithms for real-time pest detection and automated spraying adjustments.
- Scaling and Adaptation: Extend trials to diverse crop types and regions to validate effectiveness and optimize system adaptability.
- Environmental Impact Studies: Conduct comprehensive studies on long-term environmental benefits and sustainability metrics.
- Commercial Viability: Assess market readiness and potential partnerships for commercial deployment.

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