



# The Study Of Serial Queues Connected To Non-Serial Queues With Feedback And Reneging In Serial Queues And Balking In Both Types Of Queues With Finite Waiting Space

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## Abstract

A general queuing model having feedback, balking and reneging in serial queuing processes connected with non-serial queuing channels with balking in random order selection for service with finite waiting space has been studied in the present paper. Such models are of common occurrence in the administrative setup.

### 1. Introduction

Various researchers including O'Brien (1954), Barrer (1955) and Finch (1959) studied the problems of serial queues in steady-state with Poisson assumption. Singh (1984) studied the problem of serial queues introducing the concept of reneging. Singh and Singh (1994) worked on the network of queuing processes with impatient customers. Satyabir, et.al (2014) obtained steady-state solution of serial queues with feedback, balking and reneging. However, there may be situations where the serial queuing processes may be connected with non-serial queuing channels keeping the above observations in view, we in the present paper obtain the steady-state solutions for serial queuing processes with feedback, balking and reneging connected with non-serial queuing channels with balking in which

- (i) M serial queuing processes with feedback, balking and reneging connected with N non-serial queuing channels with balking.
- (ii) A customer may join any channel from outside and leave the system at any stage after getting service.

- (iii) Feedback is permitted from each channel to its previous channel in serial channels.
- (iv) The customer may balk due to long queue at each serial and non-serial service channels.
- (v) The impatient customer leaves serial service channels after wait of certain time.
- (vi) The input process in serial and non-serial channels depends upon queue size and Poisson arrivals are followed. Exponential service times are followed.
- (vii) The queue discipline is random selection for service and Waiting space is finite.

**Key Words:** Steady-State solutions, difference-differential, serial and non-serial channels, waiting space, random selection, Poisson arrivals, exponential service, feedback, balking and reneging.

## 2. Formulation of the Model

The system consists of the serial queues  $Q_j (j=1,2,3,\dots,M)$  and non-serial channels  $Q_i (i=1,2,3,\dots,N)$  with respective servers  $S_j (j=1,2,3,\dots,M)$  and  $S_i (i=1,2,3,\dots,N)$ . Customers demanding different types of service arrive from outside the system in Poisson stream with parameters  $\lambda_j (j=1,2,3,\dots,M)$  and  $\lambda_i (i=1,2,3,\dots,N)$  at  $Q_j (j=1,2,3,\dots,M)$  and  $Q_i (i=1,2,3,\dots,N)$  but the sight of long queue at  $Q_j (j=1,2,3,\dots,M)$  and  $Q_i (i=1,2,3,\dots,N)$  may discourage the fresh customer from joining it and may decide not to enter the service channel at  $Q_j (j=1,2,3,\dots,M)$  and  $Q_i (i=1,2,3,\dots,N)$ . Then the Poisson input rate at  $Q_j (j=1,2,3,\dots,M)$  and  $Q_i (i=1,2,3,\dots,N)$  would be  $\frac{\lambda_j}{n_j + 1}$  where  $n_j$  is the queue size of  $Q_j (j=1,2,3,\dots,M)$  and  $\frac{\lambda_i}{m_i + 1}$  where  $m_i$  is the queue size of  $Q_i (i=1,2,3,\dots,N)$ . Further, the impatient customer joining any serial service channel  $Q_j (j=1,2,3,\dots,M)$  may leave the queue without getting service after wait of certain time. Here  $C_{in_i}$  is the reneging rate at which customer renege after a wait of time  $T_{0i}$  whenever there are  $n_i$  customer in the service channel  $Q_i$ .

$$C_{in_i} = \frac{\mu_i e^{-\frac{\mu_i T_{0i}}{n_i}}}{1 - e^{-\frac{\mu_i T_{0i}}{n_i}}} \quad (i=1,2,3,\dots,M). \text{ Service time distributions for servers } S_j (j=1,2,3,\dots,M)$$

and  $S_i (i=1,2,3,\dots,N)$  are mutually independent negative exponential distribution with parameters  $\mu_j (j=1,2,\dots,M)$  and  $\mu_i (i=1,2,3,\dots,N)$  respectively. After the completion of service at  $S_j$ , the

customer either leaves the system with probability  $p_j$  or joins the next channel with probability  $\frac{q_j}{n_{j+1} + 1}$

or join back the previous channel with probability  $\frac{r_j}{n_{j-1} + 1}$  such that  $p_j + \frac{q_j}{n_{j+1} + 1} + \frac{r_j}{n_{j-1} + 1} = 1$  ( $j = 1, 2, 3, \dots, M - 1$ ) and after the completion of service at  $S_M$  the customer either leaves the system with probability  $p_M$  or joins back the previous channel with probability  $\frac{r_M}{n_{M-1} + 1}$  or joins any queue

$Q_i$  ( $i = 1, 2, 3, \dots, N$ ) with probability  $\frac{q_{Mi}}{m_i + 1}$  ( $i = 1, 2, 3, \dots, N$ ) such that

$p_M + \frac{r_M}{n_{M-1} + 1} + \sum_{i=1}^N \frac{q_{Mi}}{m_i + 1} = 1$ . It is being mentioned here that  $r_j = 0$  for  $j = 1$  as there is no previous

channel of the first channel.

### 3. Formulation of Equations:

Define:  $P(n_1, n_2, n_3, \dots, n_{M-1}, n_M, m_1, m_2, m_3, \dots, m_{N-1}, m_N; t)$  = the probability that at time 't' there are  $n_j$  customers (which may balk, renege or leave the system after being serviced or join the next phase or join back the previous channel) waiting before  $S_j$  ( $j = 1, 2, 3, \dots, M - 1, M$ );  $m_i$  customers (which may leave the system after being serviced) waiting before the servers  $S_{li}$  ( $i = 1, 2, 3, \dots, N$ ).

We define the operators  $T_{i\cdot}, T_{\cdot i}, T_{\cdot, i+1}, T_{i-1, \cdot i}$  to act upon the vectors  $\tilde{n} = (n_1, n_2, n_3, \dots, n_M)$  or  $\tilde{m} = (m_1, m_2, m_3, \dots, m_N)$  as follows

$$\begin{aligned} T_{i\cdot}(\tilde{n}) &= (n_1, n_2, n_3, \dots, n_i - 1, \dots, n_M) \\ T_{\cdot i}(\tilde{n}) &= (n_1, n_2, n_3, \dots, n_i + 1, \dots, n_M) \\ T_{\cdot, i+1}(\tilde{n}) &= (n_1, n_2, n_3, \dots, n_i + 1, n_{i+1} - 1, \dots, n_M) \\ T_{i-1, \cdot i}(\tilde{n}) &= (n_1, n_2, n_3, \dots, n_{i-1} - 1, n_i + 1, \dots, n_M) \end{aligned}$$

Here we assume that at any instant there are K customers in the system i.e.  $\sum_{i=1}^M n_i + \sum_{j=1}^N m_j = K$ .

Then the customers arriving at that instant will not be allowed to join the system and is considered lost for the system.

Following the procedure given by Kelly (1979), we write the difference – differential equations as

$$\begin{aligned} \frac{dP(\tilde{n}, \tilde{m}; t)}{dt} &= - \left[ \sum_{i=1}^M \frac{\lambda_i}{n_i + 1} + \sum_{i=1}^M \delta(n_i) (\mu_i + C_{m_i}) + \sum_{j=1}^N \frac{\lambda_j}{m_j + 1} + \sum_{j=1}^N \delta(m_j) \mu_j \right] P(\tilde{n}, \tilde{m}; t) + \sum_{i=1}^M \frac{\lambda_i}{n_i} P(T_{i\cdot}(\tilde{n}), \tilde{m}; t) \\ &+ \sum_{i=1}^M (\mu_i P_i + C_{m_{i+1}}) P(T_{\cdot i}(\tilde{n}), \tilde{m}; t) \\ &+ \sum_{i=1}^{M-1} \mu_i \frac{q_i}{n_{i+1}} P(T_{\cdot, i+1}(\tilde{n}), \tilde{m}; t) + \sum_{i=1}^M \mu_i \frac{r_i}{n_{i-1}} P(T_{i-1, \cdot i}(\tilde{n}), \tilde{m}; t). \\ &+ \sum_{j=1}^N \mu_M \frac{q_{Mj}}{m_j} P(n_1, n_2, \dots, n_M + 1, T_j(\tilde{m}); t) \\ &+ \sum_{j=1}^N \frac{\lambda_j}{m_j} P(\tilde{n}, T_j(\tilde{m}); t) + \sum_{j=1}^N \mu_j P(\tilde{n}, T_{\cdot j}(\tilde{m}); t) \end{aligned} \quad (3.1)$$

for  $n_i \geq 0$  ( $i=1,2,3,\dots,M$ ),  $m_j \geq 0$  ( $j=1,2,3,\dots,N$ );

where  $\delta(x) = \begin{cases} 1 & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$  and  $\sum_{i=1}^M n_i + \sum_{j=1}^N m_j < K$ .

$$\frac{dP(\tilde{n}, \tilde{m}; t)}{dt} = - \left[ \sum_{i=1}^M \delta(n_i) (\mu_i + C_{m_i}) + \sum_{j=1}^N \delta(m_j) \mu_{1j} \right] P(\tilde{n}, \tilde{m}; t) + \sum_{i=1}^M \frac{\lambda_i}{n_i} P(T_i \cdot (\tilde{n}), \tilde{m}; t) + \sum_{i=1}^{M-1} \mu_i \frac{q_i}{n_{i+1}} P(T_{i,i+1} \cdot (\tilde{n}), \tilde{m}; t) \\ + \sum_{i=1}^M \mu_i \frac{r_i}{n_{i-1}} P(T_{i-1,i} \cdot (\tilde{n}), \tilde{m}; t) + \sum_{j=1}^N \mu_M \frac{q_{Mj}}{m_j} P(n_1, n_2, \dots, n_M + 1, T_j \cdot (\tilde{m}); t) + \sum_{j=1}^N \frac{\lambda_{1j}}{m_j} P(\tilde{n}, T_j \cdot (\tilde{m}); t)$$

for  $n_i \geq 0$  ( $i=1,2,3,\dots,M$ ),  $m_j \geq 0$  ( $j=1,2,3,\dots,N$ ); (3.2)

where  $\delta(x) = \begin{cases} 1 & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$  and  $\sum_{i=1}^M n_i + \sum_{j=1}^N m_j = K$ .

#### 4. Steady-State Equations

We write the following steady-state equations of the queuing model by equating the time derivative to zero in equations (3.1) and (3.2):

$$\left[ \sum_{i=1}^M \frac{\lambda_i}{n_i + 1} + \sum_{i=1}^M \delta(n_i) (\mu_i + C_{m_i}) + \sum_{j=1}^N \frac{\lambda_{1j}}{m_j} + \sum_{j=1}^N \delta(m_j) \mu_{1j} \right] P(\tilde{n}, \tilde{m}) = \sum_{i=1}^M \frac{\lambda_i}{n_i} P(T_i \cdot (\tilde{n}), \tilde{m}) + \sum_{i=1}^M (\mu_i P_i + C_{m_{i+1}}) P(T_{i,i+1} \cdot (\tilde{n}), \tilde{m}) \\ + \sum_{i=1}^{M-1} \mu_i \frac{q_i}{n_{i+1}} P(T_{i,i+1} \cdot (\tilde{n}), \tilde{m}) + \sum_{i=1}^M \mu_i \frac{r_i}{n_{i-1}} P(T_{i-1,i} \cdot (\tilde{n}), \tilde{m}) \\ + \sum_{j=1}^N \mu_M \frac{q_{Mj}}{m_j} P(n_1, n_2, \dots, n_M + 1, T_j \cdot (\tilde{m})) \\ + \sum_{j=1}^N \frac{\lambda_{1j}}{m_j} P(\tilde{n}, T_j \cdot (\tilde{m})) + \sum_{j=1}^N \mu_{1j} P(\tilde{n}, T_j \cdot (\tilde{m}))$$

for  $n_i \geq 0$  ( $i=1,2,3,\dots,M$ ),  $m_j \geq 0$  ( $j=1,2,3,\dots,N$ );

$\delta(x) = \begin{cases} 1 & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$  and  $\sum_{i=1}^M n_i + \sum_{j=1}^N m_j < K$ .

$$\left[ \sum_{i=1}^M \delta(n_i) (\mu_i + C_{m_i}) + \sum_{j=1}^N \delta(m_j) \mu_{1j} \right] P(\tilde{n}, \tilde{m}; t) = \sum_{i=1}^M \frac{\lambda_i}{n_i} P(T_i \cdot (\tilde{n}), \tilde{m}; t) \\ + \sum_{i=1}^{M-1} \mu_i \frac{q_i}{n_{i+1}} P(T_{i,i+1} \cdot (\tilde{n}), \tilde{m}; t) + \sum_{i=1}^M \mu_i \frac{r_i}{n_{i-1}} P(T_{i-1,i} \cdot (\tilde{n}), \tilde{m}; t) \\ + \sum_{j=1}^N \mu_M \frac{q_{Mj}}{m_j} P(n_1, n_2, \dots, n_M + 1, T_j \cdot (\tilde{m}); t) + \sum_{j=1}^N \frac{\lambda_{1j}}{m_j} P(\tilde{n}, T_j \cdot (\tilde{m}); t)$$

where  $n_i \geq 0$  ( $i=1,2,3,\dots,M$ ),  $m_j \geq 0$  ( $j=1,2,3,\dots,N$ ); and  $\sum_{i=1}^M n_i + \sum_{j=1}^N m_j = K$ .

#### 5. Steady-State Solutions

The steady state solutions of equations (4.1) and (4.2) can be verified as

$$P(\tilde{n}, \tilde{m}) = P(\tilde{0}, \tilde{0}) \left( \frac{1}{n_1!} \frac{\left( \lambda_1 + \frac{\mu_2 r_2 \rho_2}{(n_2 + 1)(\mu_2 + C_{2n_2+1})} \right)^{n_1}}{\prod_{i=1}^{n_1} (\mu_i + C_{1i})} \right) \cdot \left( \frac{1}{n_2!} \frac{\left( \lambda_2 + \frac{\mu_1 q_1 \rho_1}{(n_1 + 1)(\mu_1 + C_{1n_1+1})} + \frac{\mu_3 r_3 \rho_3}{(n_3 + 1)(\mu_3 + C_{3n_3+1})} \right)^{n_2}}{\prod_{i=1}^{n_2} (\mu_i + C_{2i})} \right)$$

$$\left( \frac{1}{n_3!} \left( \lambda_3 + \frac{\mu_2 q_2 \rho_2}{(n_2+1)(\mu_2 + C_{2n_2+1})} + \frac{\mu_4 r_4 \rho_4}{(n_4+1)(\mu_4 + C_{4n_4+1})} \right)^{n_3} \right) \dots$$

$$\left( \frac{1}{n_{M-1}!} \left( \lambda_{M-1} + \frac{\mu_{M-2} q_{M-2} \rho_{M-2}}{(n_{M-2}+1)(\mu_{M-2} + C_{M-2n_{M-2}+1})} + \frac{\mu_M r_M \rho_M}{(n_M+1)(\mu_M + C_{Mn_M+1})} \right)^{n_{M-1}} \right)$$

$$\left( \frac{1}{n_M!} \left( \lambda_M + \frac{\mu_{M-1} q_{M-1} \rho_{M-1}}{(n_{M-1}+1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \right)^{n_M} \right) \cdot \frac{1}{m_1!} \left( \lambda_{11} + \frac{\mu_M q_{M1} \rho_M}{(n_M+1)(\mu_M + C_{Mn_M+1})} \right)^{m_1}$$

$$\cdot \frac{1}{m_2!} \left( \lambda_{12} + \frac{\mu_M q_{M2} \rho_M}{(n_M+1)(\mu_M + C_{Mn_M+1})} \right)^{m_2} \dots \frac{1}{m_N!} \left( \lambda_{1N} + \frac{\mu_M q_{MN} \rho_M}{(n_M+1)(\mu_M + C_{Mn_M+1})} \right)^{m_N}$$

(5.1)

Where

$$\rho_1 = \lambda_1 + \frac{\mu_2 r_2 \rho_2}{(n_2+1)(\mu_2 + C_{2n_2+1})}$$

$$\rho_2 = \left( \lambda_2 + \frac{\mu_1 q_1 \rho_1}{(n_1+1)(\mu_1 + C_{1n_1+1})} + \frac{\mu_3 r_3 \rho_3}{(n_3+1)(\mu_3 + C_{3n_3+1})} \right)$$

$$\rho_3 = \lambda_3 + \frac{\mu_2 q_2 \rho_2}{(n_2+1)(\mu_2 + C_{2n_2+1})} + \frac{\mu_4 r_4 \rho_4}{(n_4+1)(\mu_4 + C_{4n_4+1})}$$

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$$\rho_{M-1} = \lambda_{M-1} + \frac{\mu_{M-2} q_{M-2} \rho_{M-2}}{(n_{M-2}+1)(\mu_{M-2} + C_{M-2n_{M-2}+1})} + \frac{\mu_M r_M \rho_M}{(n_M+1)(\mu_M + C_{Mn_M+1})}$$

$$\rho_M = \lambda_M + \frac{\mu_{M-1} q_{M-1} \rho_{M-1}}{(n_{M-1}+1)(\mu_{M-1} + C_{M-1n_{M-1}+1})}$$

(5.2)

solving these (5.2) M-equations for  $\rho_M$  with the help of determinants, we get

$$\rho_M = \left( \lambda_M \Delta_{M-1} + \frac{q_{M-1} \mu_{M-1}}{(n_{M-1} + 1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \lambda_{M-1} \Delta_{M-2} + \frac{q_{M-1} \mu_{M-1}}{(n_{M-1} + 1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \cdot \frac{q_{M-2} \mu_{M-2}}{(n_{M-2} + 1)(\mu_{M-2} + C_{M-2n_{M-2}+1})} \lambda_{M-2} \Delta_{M-3} + \dots + \frac{q_{M-1} \mu_{M-1}}{(n_{M-1} + 1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \cdot \frac{q_{M-2} \mu_{M-2}}{(n_{M-2} + 1)(\mu_{M-2} + C_{M-2n_{M-2}+1})} \dots \cdot \frac{q_3 \mu_3}{(n_3 + 1)(\mu_3 + C_{3n_3+1})} \cdot \frac{q_2 \mu_2}{(n_2 + 1)(\mu_2 + C_{2n_2+1})} \lambda_2 \Delta_1 + \frac{q_{M-1} \mu_{M-1}}{(n_{M-1} + 1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \cdot \frac{q_{M-2} \mu_{M-2}}{(n_{M-2} + 1)(\mu_{M-2} + C_{M-2n_{M-2}+1})} \dots \cdot \frac{q_3 \mu_3}{(n_3 + 1)(\mu_3 + C_{3n_3+1})} \cdot \frac{q_2 \mu_2}{(n_2 + 1)(\mu_2 + C_{2n_2+1})} \cdot \frac{q_1 \mu_1}{(n_1 + 1)(\mu_1 + C_{1n_1+1})} \lambda_1 \right) \Delta_{M-2} \quad (5.3)$$

Where,

$$\Delta_M =$$

$$\Delta_{M-1} - \frac{q_{M-1} \mu_{M-1}}{(n_{M-1} + 1)(\mu_{M-1} + C_{M-1n_{M-1}+1})} \cdot \frac{r_M \mu_M}{(n_M + 1)(\mu_M + C_{Mn_M+1})} \Delta_{M-2}$$

Where

$$\Delta_1 = 1 \quad \Delta_2 = \left| \begin{array}{c} 1 \\ - \frac{\frac{r_2 \mu_2}{n_2 + 1}}{\mu_2 + c_{2n_2+1}} \end{array} \right| \quad \Delta_3 = \left| \begin{array}{ccc} 1 & - \frac{\frac{r_2 \mu_2}{n_2 + 1}}{\mu_2 + c_{2n_2+1}} & 0 \\ \frac{\frac{q_1 \mu_1}{n_1 + 1}}{\mu_1 + c_{1n_1+1}} & 1 & - \frac{\frac{r_3 \mu_3}{n_3 + 1}}{\mu_3 + c_{3n_3+1}} \\ 0 & - \frac{\frac{q_2 \mu_2}{n_2 + 1}}{\mu_2 + c_{2n_2+1}} & 1 \end{array} \right| \dots \quad (5.4)$$

$$\Delta_M = \begin{vmatrix} 1 & -\frac{r_2 \mu_2}{n_2 + 1} & 0 & 0 & \dots & 0 & 0 & 0 \\ \frac{q_1 \mu_1}{n_1 + 1} & 1 & -\frac{r_3 \mu_3}{n_3 + 1} & 0 & \dots & 0 & 0 & 0 \\ 0 & -\frac{q_2 \mu_2}{n_2 + 1} & 1 & -\frac{r_4 \mu_4}{n_4 + 1} & \dots & 0 & 0 & 0 \\ \dots & \dots \\ 0 & 0 & 0 & 0 & \dots & -\frac{q_{M-2} \mu_{M-2}}{n_{M-2} + 1} & 1 & -\frac{r_M \mu_M}{n_M + 1} \\ 0 & 0 & 0 & 0 & \dots & 0 & -\frac{q_{M-1} \mu_{M-1}}{n_{M-1} + 1} & 1 \end{vmatrix}$$

Since  $\rho_M$  is obtained, so we can get  $\rho_{M-1}$  by putting the value of  $\rho_M$  in the last equation of (5.2),  $\rho_{M-2}$  by putting the values of  $\rho_{M-1}$  and  $\rho_M$  in the last but one equation of (5.2). Continuing in this way, we shall obtain  $\rho_{M-3}, \rho_{M-4}, \dots, \rho_3, \rho_2$  and  $\rho_1$ .

Thus, we write (5.1) as under

$$p(\tilde{n}, \tilde{m}) = P(\tilde{0}, \tilde{0}) \left( \frac{1}{n_1!} \frac{(\rho_1)^{n_1}}{\prod_{i=1}^{n_1} (\mu_1 + C_{1i})} \right) \left( \frac{1}{n_2!} \frac{(\rho_2)^{n_2}}{\prod_{i=1}^{n_2} (\mu_2 + C_{2i})} \right) \dots \left( \frac{1}{n_{M-1}!} \frac{(\rho_{M-1})^{n_{M-1}}}{\prod_{i=1}^{n_{M-1}} (\mu_{M-1} + C_{M-1i})} \right) \cdot \left( \frac{1}{n_M!} \frac{(\rho_M)^{n_M}}{\prod_{i=1}^{n_M} (\mu_M + C_{Mi})} \right) \cdot \frac{1}{m_1!} \left( \frac{\lambda_{11} + \frac{\mu_M q_{M1} \rho_M}{(n_M + 1)(\mu_M + C_{Mn_M + 1})}}{\mu_{11}} \right)^{m_1} \cdot \frac{1}{m_2!} \left( \frac{\lambda_{12} + \frac{\mu_M q_{M2} \rho_M}{(n_M + 1)(\mu_M + C_{Mn_M + 1})}}{\mu_{12}} \right)^{m_2} \dots \frac{1}{m_N!} \left( \frac{\lambda_{1N} + \frac{\mu_M q_{MN} \rho_M}{(n_M + 1)(\mu_M + C_{Mn_M + 1})}}{\mu_{1N}} \right)^{m_N} \tag{5.5}$$

$$n_i \geq 0 \quad (i = 1, 2, 3, \dots, M), m_j \geq 0 \quad (j = 1, 2, 3, \dots, N)$$

We obtain  $P(\tilde{0}, \tilde{0})$  from the normalizing conditions.

$$\sum_{\tilde{n}=\tilde{0}, \tilde{m}=\tilde{0}}^{\infty} P(\tilde{n}, \tilde{m}) = 1 \tag{5.6}$$

and with the restriction that traffic intensity of each service channel of the system is less than unity. Here it is mentioned that the customers leave the system at constant rate as long as there is a line, provided that the customers are served in the order in which they arrive. Putting  $C_{in_i} = C_i \quad (i = 1, 2, 3, \dots, M)$  in the steady-state solution (5.1) then  $\rho_i \quad (i = 1, 2, 3, \dots, M)$  will change accordingly and the steady-state solution reduces to

$$\begin{aligned}
P(\tilde{n}, \tilde{m}) = P(\tilde{0}, \tilde{0}) & \left( \frac{1}{n_1!} \left( \frac{\rho_1}{\mu_1 + C_1} \right)^{n_1} \right) \left( \frac{1}{n_2!} \left( \frac{\rho_2}{\mu_2 + C_2} \right)^{n_2} \right) \left( \frac{1}{n_3!} \left( \frac{\rho_3}{\mu_3 + C_3} \right)^{n_3} \right) \dots \\
& \left( \frac{1}{n_{M-1}!} \left( \frac{\rho_{M-1}}{\mu_{M-1} + C_{M-1}} \right)^{n_{M-1}} \right) \left( \frac{1}{n_M!} \left( \frac{\rho_M}{\mu_M + C_M} \right)^{n_M} \right) \\
& \cdot \frac{1}{m_1!} \left( \frac{\lambda_{11} + \frac{\mu_M q_{M1} \rho_M}{(n_M + 1)(\mu_M + C_M)}}{\mu_{11}} \right)^{m_1} \cdot \frac{1}{m_2!} \left( \frac{\lambda_{12} + \frac{\mu_M q_{M2} \rho_M}{(n_M + 1)(\mu_M + C_M)}}{\mu_{12}} \right)^{m_2} \\
& \dots \frac{1}{m_N!} \left( \frac{\lambda_{1N} + \frac{\mu_M q_{MN} \rho_M}{(n_M + 1)(\mu_M + C_M)}}{\mu_{1N}} \right)^{m_N}
\end{aligned} \tag{5.7}$$

We obtain  $P(\tilde{0}, \tilde{0})$  from (5.6) and (5.7) as

$$\left( P(\tilde{0}, \tilde{0}) \right)^{-1} = \prod_{i=1}^M e^{\frac{\rho_i}{\mu_i + C_i}} \prod_{j=1}^N e^{\rho_j}$$

$$\text{Where } \rho_{1j} = \frac{\lambda_{1j} + \frac{\mu_M q_{Mj} \rho_M}{(n_M + 1)(\mu_M + C_M)}}{\mu_{1j}}, \quad j = 1, 2, 3, \dots, N$$

Thus  $P(\tilde{n}, \tilde{m})$  is completely determined.

### **ACKNOWLEDGEMENT:**

I would like to thank my family and colleagues in my college for support in doing my research.

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