



Land Slide Detection And Traffic Automation

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Abstract: This paper gives a real-time landslide detection and traffic automation system based on ADXL sensors, IR sensors, and rain sensors. The system gives real-time alerts using an LCD display and manages traffic by motorized gates. Road safety and accident avoidance are enhanced with wireless communication based on Zigbee and emergency notification based on GSM.

KEYWORDS: Landslide detection, traffic automation, ADXL sensor, IR sensor, rain sensor, ESP 32, Zigbee communication, GSM module, road safety, real-time monitoring.

I. INTRODUCTION

Landslides are a prevalent natural disaster causing immense damage to transportation safety in mountainous and hilly regions. Unfavorable weather patterns, heavy precipitation, and earthquake activities are prime factors for rising landslide risks and subsequent road congestion, accidents, and fatalities. Road safety management in these places necessitates the need for effective and real-time monitoring systems capable of identifying oncoming landslides and giving warning to drivers and authorities alike.

This paper suggests a landslide detection and traffic automation system incorporating several sensors, such as ADXL accelerometers, IR sensors, and rain sensors, to track ground vibration, vehicle travel, and intensity of rain. This paper is equipped with an ESP 32 microcontroller for data processing, LCD display for real-time alerts, and Zigbee communication for wireless transmission. Motorized gates control traffic flow in accordance with the hazards detected, and a GSM module guarantees emergency messages are sent to the concerned authorities.

An automated and scalable solution is deployed through this system, which boosts road safety, minimizes the risk of accidents, and increases emergency response time. Future improvements can involve AI-driven predictive models and IoT-enabled cloud monitoring for further streamlining traffic management in landslide-prone areas.

II. RELATED WORKS

In 2012, H. Gupta et al. suggested a wireless early warning system for landslide incorporating geophones and GSM telecommunication to detect ground vibration and provide alerts to the authorities ^[1]. Subsequently, in 2014, S. Patel et al. designed a MEMS-based landslide early warning system, utilizing rain sensors and accelerometers to observe ground tilt and rainfall intensity for enhanced response time for emergency reaction ^[2]. In 2015, P. Das et al. proposed an infrared sensor-based collision warning system for mountainous roads. The system employed IR sensors to sense vehicles on blind curves and presented real-time warnings on roadside LCD displays ^[3]. One year later, in 2016, Y. Chen et al. proposed a real-time IoT-based landslide prediction model, incorporating wireless sensor networks (WSNs) and cloud computing to examine soil movement patterns and forecast landslides ^[4]. In 2018, L. Zhang et al. introduced a deep learning-based landslide detection system based on satellite images and convolutional neural networks (CNNs). The research

proved that CNN models were capable of classifying landslide-prone regions with high accuracy, enhancing the accuracy of hazard prediction over conventional methods ^[5]. Subsequently, in 2019, M. Sharma et al. created an automatic traffic management system with IR sensors, Zigbee, and motor gates to manage the flow of vehicles in hilly roadways, decreasing accidents in inner curves ^[6]. N. Singh et al. presented a multi-sensor IoT landslide detection system in 2020, incorporating ADXL accelerometers, rain gauges, and GSM modules, to alert drivers and authorities in real-time of landslides ^[7]. In the same year, R. Kumar et al. deployed drone-based landslide monitoring, using UAVs carrying thermal and LiDAR sensors to image dangerous slopes and evaluate landslide risk ^[8]. In 2022, A. Verma et al. came up with a machine learning-powered early warning system to detect landslide that utilized past landslide history and real-time sensor data for predicting landslide occurrences. The model proved to be more accurate in landslide prediction, enabling authorities to take preventive measures ^[9]. Very recently, in 2023, J. Lee et al. proposed a 5G-based landslide detection and traffic automation system, combining real-time IoT sensors, AI-aided traffic monitoring, and remote drone surveillance to offer improved, faster, and more efficient landslide detection and response mechanisms. The experimental results indicated that the 5G-based system offered considerable improvement in response time and communication reliability in landslide-conditioned regions ^[10].

III. PROPOSED MODEL

This paper introduces an intelligent landslide detection and traffic automation system intended to improve road safety in landslide hotspots. The system comprises a Hub Model and a Vehicle Model, with the Hub Model receiving real-time readings from an ADXL accelerometer sensor of ground vibrations, a rain sensor of rainfall intensity, and IR sensors of vehicle proximity. This information is processed through an Arduino-based control unit, which sends alerts through LCD screens, buzzers, and automated traffic gates to control vehicle flow.

The Vehicle Model, deployed on vehicles, gets hazard notifications from the Hub Model via Zigbee communication, flashing warnings to drivers and buzzing buzzer alarms. Moreover, a GSM module ensures emergency messages are dispatched to authorities for immediate response. By combining real-time environment monitoring, wireless communication, and automatic traffic control, the new model enhances road safety significantly, reduces accident risk, and ensures smooth traffic flow in dangerous environments.

A. Hub Model:

The Hub Model is a centralized device installed in landslide-susceptible locations to track environmental and vehicle conditions. It gathers real-time information from an ADXL accelerometer sensor for ground motions, a rain sensor for rainfall amount, and IR sensors for detecting vehicles. The processing unit based on ESP 32 processes this information and initiates suitable safety responses, including showing alerts on LCD displays, sounding buzzers, and operating automated traffic gates. This model provides early detection of hazards and active traffic control to avoid accidents in risky areas.

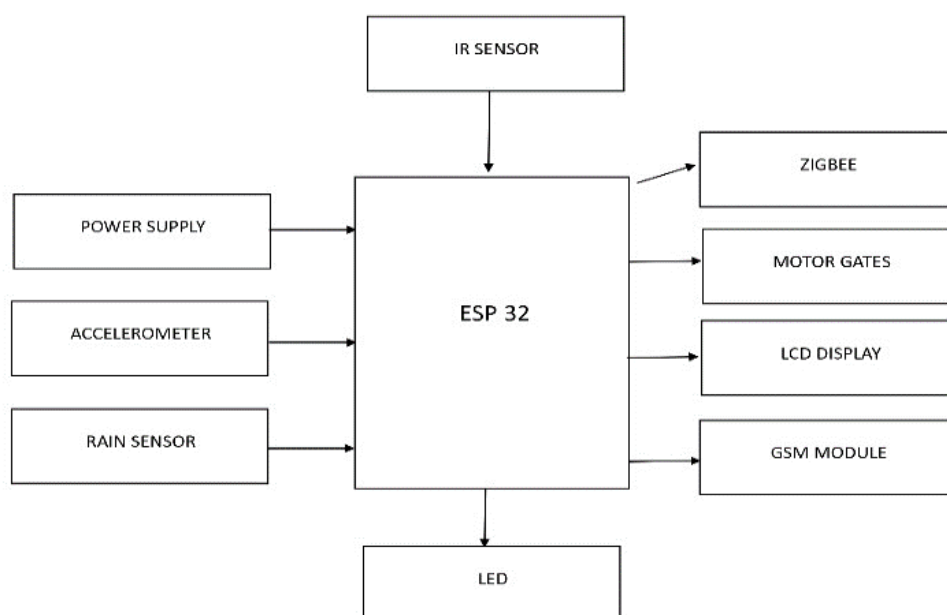


Fig.1 Hub Model

The operation of the hub model is dependent on real-time data acquisition, processing, and automated response to promote road safety in landslide-prone areas. The system begins by constantly monitoring environmental conditions through the sensors linked to the ESP 32. The accelerometer senses vibrations on the ground, which can signal an oncoming landslide. Simultaneously, the rain sensor gauges rainfall intensity, giving vital information amount of rain in that area. The infrared sensor senses the incoming vehicles in the vicinity, assisting in the regulation of traffic control measures when required.

Once the ESP 32 has received data from these sensors, it processes the data to establish whether there is a dangerous condition. In the event of the sensed vibration or rain surpassing a predetermined threshold, the system initiates warning systems. The Zigbee module sends wireless warnings to passing vehicles with a receiver, alerting drivers to imminent hazards on the road ahead. Concurrently, the system switches on motorized traffic gates to limit vehicle travel in risk areas, avoiding accidents. The GSM module also sends emergency alerts to authorities, facilitating rapid response measures to avert risks.

The power supply guarantees operation of all parts of the hub model at all times to ensure system reliability. The autonomous nature of this model minimizes human involvement while guaranteeing effective hazard detection and traffic management. Through the use of real-time sensing, wireless communication, and automated traffic management, the hub model increases road safety and reduces the effect of landslides on transport infrastructure.

B. Vehicle Model:

The vehicle model is configured to get hazard notifications from the hub model and give real-time alerts to drivers. It has an ESP 32, a Zigbee communication module for wireless communication, an LCD display for visual alerting, and a buzzer for audio warning. The Zigbee module gets notification from the hub model whenever a possible landslide or dangerous situation is identified. When the alert is received, the ESP 32 interprets the signal and activates the LCD display to display warning messages, making the driver aware of the hazard on the road.

In parallel, the buzzer generates a sound alarm to catch the driver's attention instantly. The system runs on a reliable power supply, providing uninterrupted operation and reliability while traveling. Through the combination of real-time hazard sensing with wireless communication and alert systems, the car model increases road safety and reduces the chances of accidents in landslide zones.

The system is self-operating, making sure drivers are notified without the need for human intervention. The integration of visual and auditory alerts increases situational awareness, enabling drivers to take precautions in good time. This model is especially beneficial in remote or low-visibility regions where direct human observation is not feasible, offering a secondary level of safety for travelers.

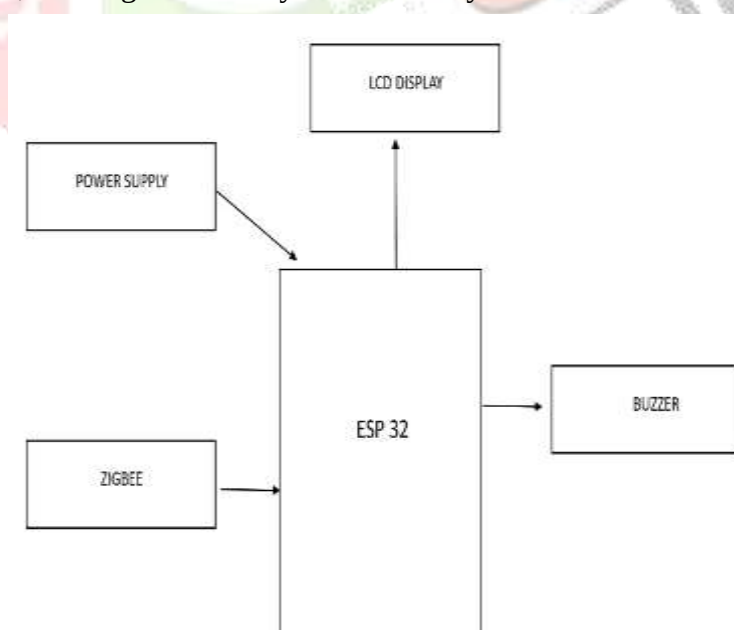


Fig 2 Vehicle Model

The operation of the vehicle model relies on getting hazard notifications from the hub model and alerting the driver by visual and auditory signals. The Zigbee communication module in the vehicle is always in listening mode for signals from the hub model, which sends alerts in the event of possible landslides or other

dangerous situations. When the Zigbee communication module gets an alert, it sends the signal to the ESP32 microcontroller, which processes the information and initiates the desired response.

When a warning sign is detected, the ESP 32 triggers the LCD display to indicate a warning message to alert the driver of the possible hazard about the landslide, the buzzer generates a loud alarm to draw the driver's attention instantly and prompt them to exercise caution. The system utilizes a stable power supply to guarantee uninterrupted operation and real-time notification of hazards.

The model operates independently, minimizing the involvement of human factors and providing prompt alerts in case of emergencies. The real-time alert system is especially beneficial during remote locations or poor weather conditions with low visibility, enabling drivers to make safe decisions to prevent possible accidents. Through the incorporation of wireless communication with automated warning systems, the vehicle model maximizes road safety and aids in the prevention of accidents in landslide-prone areas.

C. Flowchart

This system is intended to promote safety by sensing obstacles, landslides, and heavy rain through sensors such as IR, ADXL accelerometer, and rain sensors. These sensors constantly scan the environment, and upon detection of a hazard, the system sends out alerts through LEDs, LCD screens, and automatic gate control. It also transmits warning messages through communication modules such as Zigbee or GSM, providing real-time updates to authorities and travelers. By detecting hazards and responding to them automatically, this system enhances road safety, particularly in disaster-stricken areas, and makes transportation safer and more efficient.

The system starts by powering up all the sensors, such as the ADXL accelerometer, IR sensor, rain sensor, LCD, GSM module, and Zigbee communication, to get them ready for monitoring. The IR sensor constantly monitors the route for obstacles, and upon detecting any, the system sends an alert by turning the opposite side LED red and maintaining a green LED on for safe travel.

In addition, the ADXL accelerometer senses ground vibration in order to alert landslides. Once a landslide is sensed, the system automatically closes gates to avoid the movement of vehicles and triggers an alert message to the authorities. In the event that no landslide is sensed, the system continues normal monitoring.

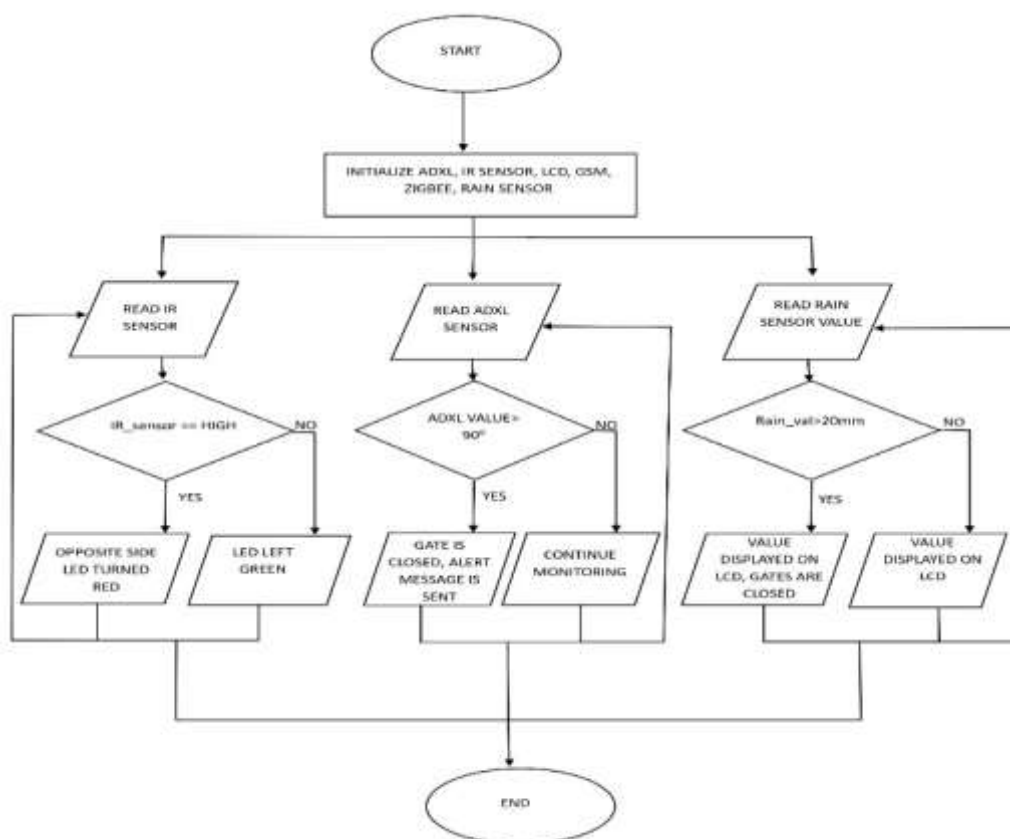


Fig.3 Flow chart

Rain sensor determines the magnitude of rain by measuring its value, and if it is more than 700, meaning heavy rain, a warning message appears on the LCD, and the gates are shut for safety purposes. If the rainfall value is less than the threshold, the LCD just shows the data without shutting the gates.

During the process, the system continuously tracks current conditions, responding dynamically by issuing warnings, regulating gate openings, and notifying authorities when necessary in order to maintain road safety and minimize accident threats..

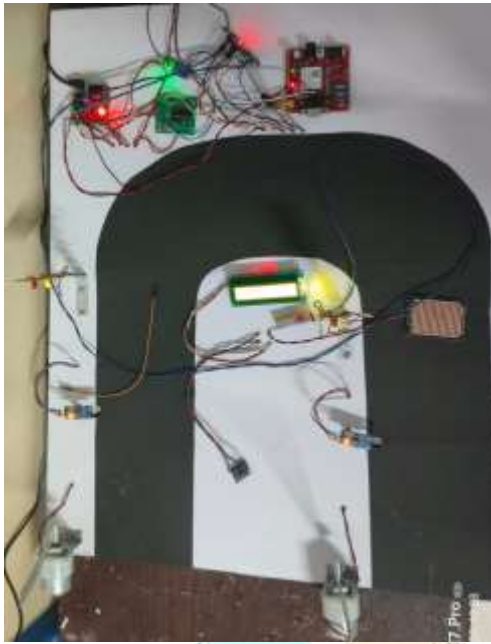


Fig.4a Hub Model when no landslide occurred

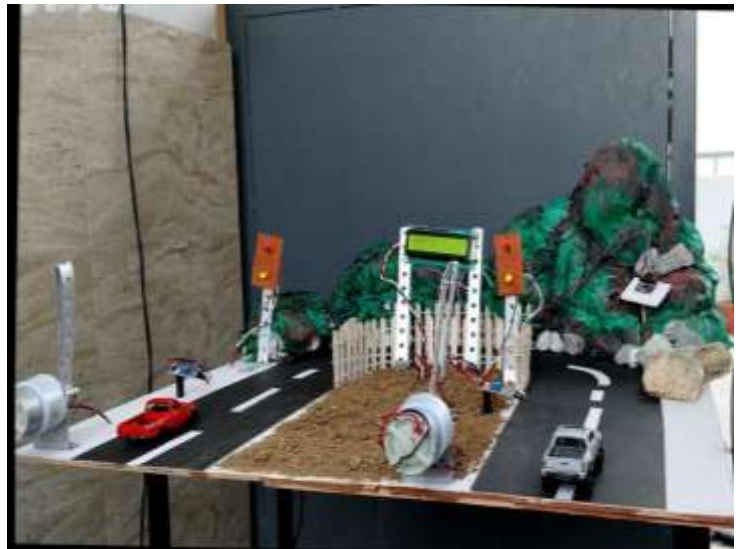


Fig.4b Fully developed Hub Model when no landslide occurred

IV. RESULT S

Fig.4 a & b represents the hub model when no landslide occurred it is observed that no message is sent through GSM and also signals are made green gates are kept open.

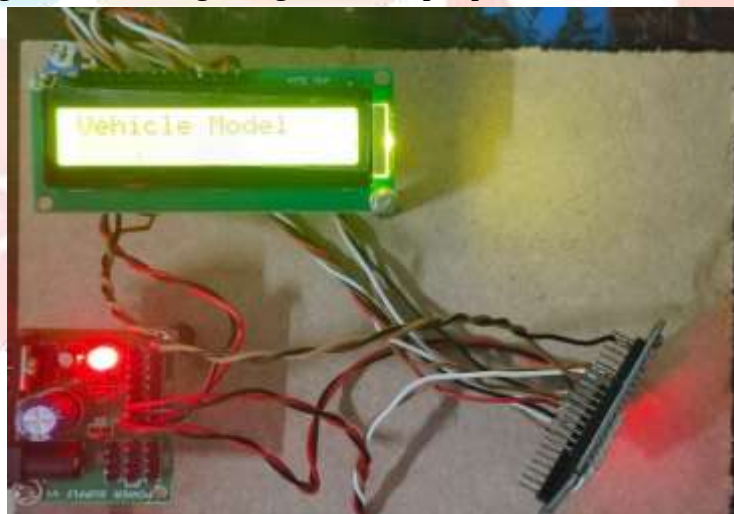


Fig.5 Vehicle Model when no landslide occurred

Fig.5 is the vehicle model which displays that it is a vehicle model when there is no landslide occurred. When the landslide is not occurred, we can observe that:

- ADXL sensor is kept not 90^0 which says that no landslide has occurred.
- The gates are kept open.

- The signals are green.
- No alert sent through ZigBee and also to vehicle model and to the authorities through GSM.

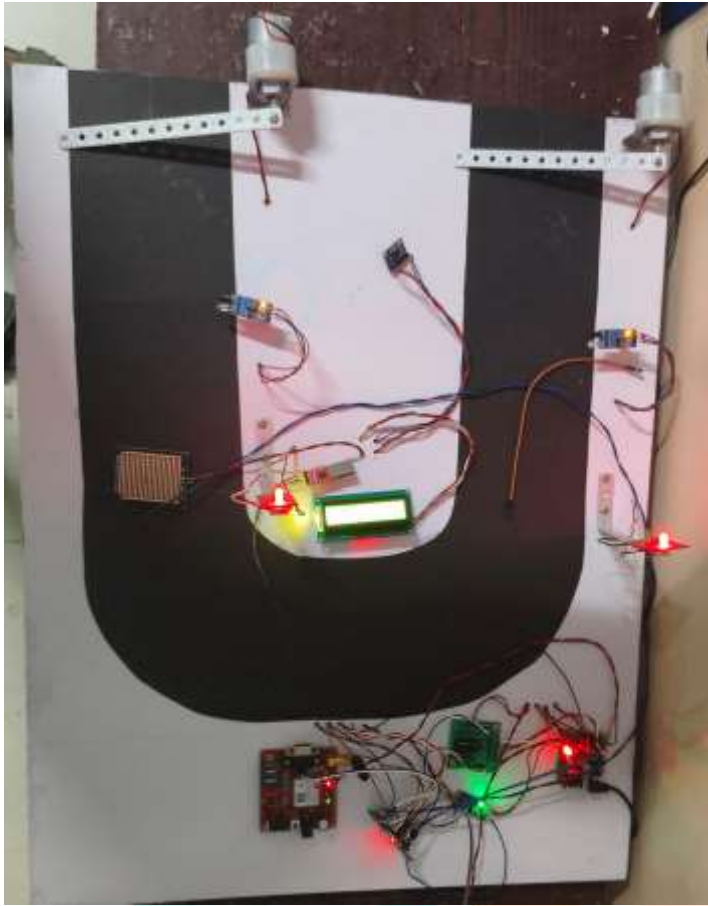
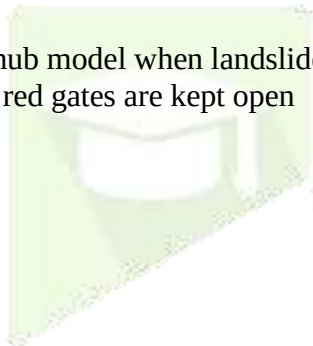
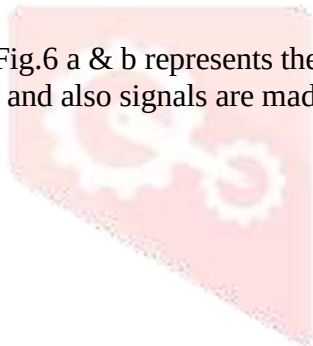


Fig.6a Hub Model when landslide occurred



Fig.6b Fully developed hub Model when landslide occurred

Fig.6 a & b represents the hub model when landslide occurred it is observed that message is sent through GSM and also signals are made red gates are kept open



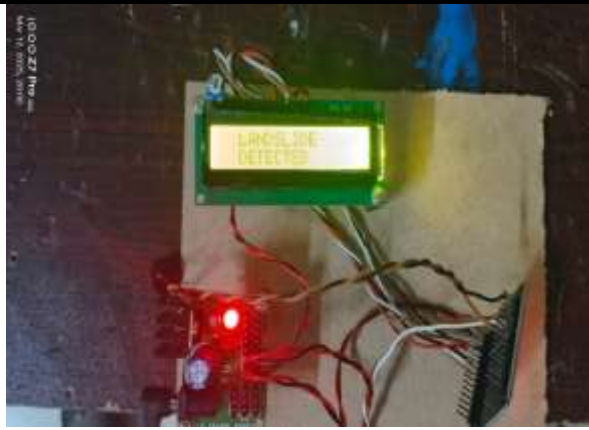


Fig.7 Vehicle Model when landslide occurred

Fig.7 is the vehicle model which displays that it is a vehicle model when the landslide occurred.

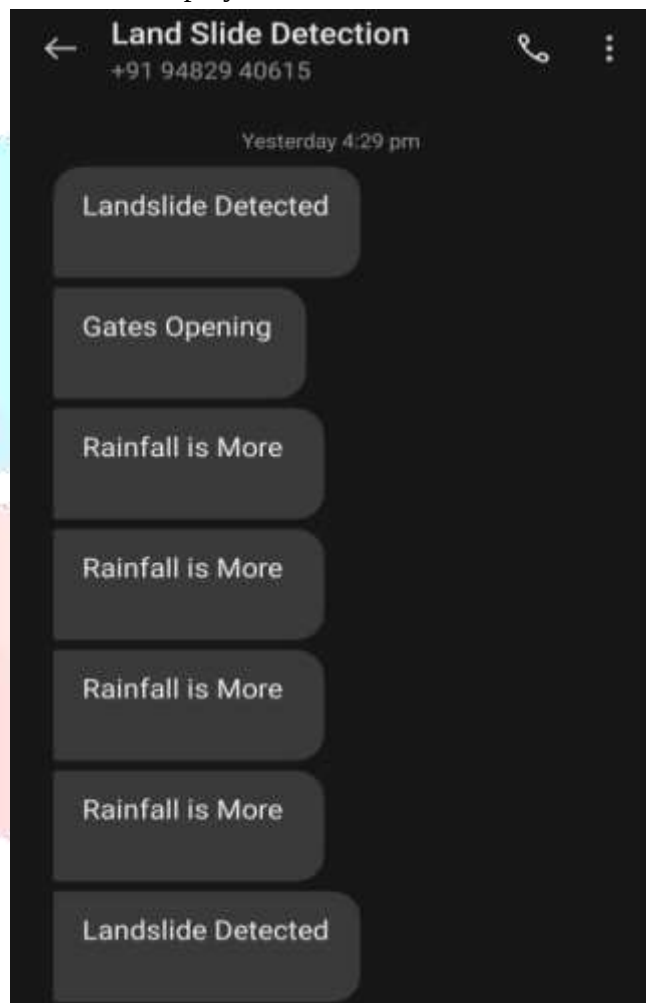


Fig.8 Screenshot of the message

Fig.8 represents the message sent through GSM for the concerned authorities about the rainfall and landslide

When landslide occurred, we can observe that:

- ADXL sensor is kept 90° which says that landslide has occurred.
- The gates are closed.
- The signals are red.
- Alert sent through zigbee and also to vehicle model and to the authorities through GSM.

V. CONCLUSION

This paper is well able to exhibit the implementation of a landslide warning and traffic automation system with MEMS accelerometers and vibration sensors. Since landslides are a primary danger in hilly and mountainous areas, particularly during monsoon seasons, early warning and responsiveness are very essential. Our proposed model aims for real-time vibration and ground motion monitoring as well as slope movements to identify potential landslide occurrences. At the point of reaching critical thresholds, the system sends instant alerts to alert surrounding travelers and authorities.

Apart from detection, the system has an automatic traffic control system, which assists in diverting or halting vehicle movement in the affected zone. This not only decreases accident chances but also regulates traffic flow effectively during crises. The system is cost-effective, simple to deploy, and extremely scalable for wide area coverage, making it ideal for extensive deployment in developing nations and remote areas.

The application of MEMS technology ensures compactness and accuracy, and the inclusion of vibration sensing provides sensitivity to slight tremors and early warnings. The dual-sensor design makes the detection system more reliable. The model is backed by microcontroller-based decision-making and real-time response with scope for future enhancement using IoT and AI technologies.

Our system closes the gap between environmental monitoring and intelligent traffic management. It is a preventive action against disasters, not a mere reactive one. The alerts so produced can be propagated to local communication networks, display boards, or even mobile apps for increased awareness.

Its implementation has high social significance since it can help save lives, avert loss of property, and aid in preparedness for disaster. The authorities can utilize the information for pre-emptive evacuation and effective traffic diversion. Residents in high-risk areas feel safer and better informed.

This paper offers a practical, reliable, and innovative way to solve two primary issues in hilly regions: landslides and traffic interruption. It creates new opportunities for disaster risk reduction through embedded systems and automation. With additions such as GPS, cloud storage, and prediction analysis, the system can develop into an entire smart disaster management system. The foundation developed here can help design safer, smarter, and quicker response environments in high-risk regions.

VI. FUTURE SCOPE

The suggested landslide detection and traffic automation system has great potential for future development and practical use. One of the key areas of development is the use of IoT (Internet of Things) technology, which would allow monitoring of sensor readings remotely via cloud platforms. This would enable authorities to monitor multiple high-risk areas from one centralized control room. The addition of artificial intelligence and machine learning would make the system more predictive by using historical and live sensor data to predict future landslides more effectively.

The inclusion of GPS and GIS mapping would enable accurate geolocation of dangers, enabling response operations to be more localized and effective for management purposes. To make the system more sustainable, solar-powered modules can be integrated, enabling the setup to be feasible even in off-grid or remote areas. A mobile app can be built to give commuters, residents, and government agencies instant alerts, enhancing the warning system's coverage and efficiency.

Additionally, existing design can be enhanced by integrating additional environmental sensors like rainfall, soil moisture, or temperature sensors to enhance detection accuracy. These extra inputs would enable a more comprehensive landslide forecasting approach.

Wireless mesh networks could also be investigated for area-wide coverage to provide strong, point-of-failure-free communication among multiple nodes of sensors. Integration with traffic control systems in place and emergency services would add further strength to the impact of the system. Finally, interface with disaster management officials can assure the system would be in step with actual-response protocols, thereby facilitating faster activation of rescue and relief efforts. These improvements would turn the current prototype into an intelligent, expandable, and effective disaster management system.

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